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OBJECTIVE

A software engineering position in a domain related to electronics and embedded applications.

EDUCATION

- 2000-2003 Master of Science in computer engineering at the National Institute of Applied Sciences (INSA : Grande Ecole), Lyon, France, Graduated with Honours
Exchange Student at QUT, Brisbane for 2 semesters (2002-2003).
Specialization : computer programming and languages, robotics
- 1998-2000 Bachelor of Science in Computer sciences at the Technology Institute of Amiens (A 2 year University program), Amiens, France, Graduated head of school
Specialization : computer programming, LAN/WAN network administration, system security
- 1995-1998 Baccalauréat Scientifique majoring in Maths and Physics;
Lycée de la Vallée du Cailly, Déville-lès-Rouen, France

COMPUTER SKILLS

Operating systems : Windows; Linux/Unix
Software : Microsoft Office
Languages : Delphi, C/C++, PHP, Java, (Visual) BASIC

LANGUAGES

French (native language); fluent English; basic Spanish

EMPLOYMENT HISTORY

- 2006 to present Employed at LDLC (www.ldlc.com) as a software engineer, Ecully, France
Responsible for the replacement of COM based middle tier server by a TCP/IP server, bringing the software engineer methodologies experience to the team of developers
- 2005 – 2006 Employed at MCO (www.mco.fr) as a software engineer, Lyon, France
Responsible for the improvement and development of ZenSolutions, bringing the JVCL experience to the team of developers
- 2003 – 2005 Employed at Opcom (www.opcom.com) as a software engineer, Brisbane, Australia
Responsible for the internationalisation of OPCrew, member of the deployment team for the SNCF (French railways)
- 2003 Research project at the Smart Devices Laboratory, QUT, Brisbane, Australia
Design and usage of neural networks applied to robot motion.
Low level hardware interfacing via wireless links

MAJOR INTERESTS

Overall coordinator of the JVCL since 2002, a component library for Delphi, C++ Builder and Kylix. Provider, among other things, of C++ Builder support and French speaking contact point.
Model trains at the HO (1:87) and Z (1:220) scale
In line roller skating